

Familial monads and structural operational semantics

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CHoCoLa Seminar
December 13, 2018

Structural operational semantics

- Notes by Plotkin (1981): method rather than theory, by example.
- Describe dynamics of programming languages, syntactically.
 - Terms from algebraic signature.
 - Dynamics as a (labelled) transition system.
 - Basic idea: describe behaviour of each operation.

$$\frac{\dots \quad x_i \xrightarrow{a_i} y_i \quad \dots}{f(x_1, \dots, x_n) \xrightarrow{a} M(y_1, \dots, y_n)}$$

Structural: behaviour of system determined by its components.

- Disturbing observation: bisimilarity in π not a congruence!

Structural $\not\Rightarrow$ compositional.

Formats

De Simone (1985): rule **format**.

- Algebraic signature + transition system specification
 \leadsto transition system.
- Specification complies with format \implies transition system behaves well.
- E.g.,
 - (weak) bisimilarity is a congruence,
 - conservative extension,
 - bisimulation up to X is sound.

A wealth of formats

Since then, lots of different formats, combining:

- negative premises,
- predicates,
- look ahead,
- terms as labels,
- variable binding,...

Functorial operational semantics

- Attempt to tame the diversity of formats and define models.
- Appealing simplicity:
 - terms = monad T ,
 - labels = comonad L ,
 - rules = distributive law $TL \rightarrow LT$.
- But not so widely adopted.
- Possible reasons:
 - too abstract,
 - not expressive enough (e.g., no negative premises or higher-order afaik),
 - does not scale well to variable binding.
- Simplifying attempt by Staton (2008):
 - SOS = monad on labeled relations.
 - Better treatment of variable binding.
 - But no clear improvement on expressiveness, and not better adopted.

Proposal

Two distinct goals:

1. Find the right language for describing
 - what goes on in proofs of congruence of bisimilarity, etc.,...
 - under which hypotheses.
2. Generate instances satisfying the hypotheses.

Here: focus on 1.

Plan

New abstract framework:

Main example	General case
cat. of transition systems functional bisimulation	transition category by lifting (cf. presheaf models)
SOS specification model partial transition proof	monad \mathcal{T} \mathcal{T} -algebra Kleisli morphism

- Morally, monad = saturation by the given rules.
- Congruence proof \Leftarrow **familiarity** of \mathcal{T} , ...
- Example with binding: π -calculus.

My first transition category

Categories that look like transition systems and functional simulations.

Baby example

(Directed, multi-)graphs, **Gph**.

- Intuitively: untyped + one label \approx rewrite systems.
- Presheaves over Γ , the category consisting of $s, t: [0] \rightrightarrows [1]$.
- **Presheaf** = contravariant functor to **Set** (Notation: $\widehat{\Gamma}$!):

$$\begin{aligned}
 G: \Gamma^{op} &\rightarrow \mathbf{Set} \\
 [0] &\mapsto V_G \\
 [1] &\mapsto E_G \\
 (s: [0] \rightarrow [1]) &\mapsto (V_G \xleftarrow{\sigma} E_G) \\
 (t: [0] \rightarrow [1]) &\mapsto (V_G \xleftarrow{\tau} E_G).
 \end{aligned}$$

Graph morphisms

Graph morphism = natural transformation = **functional simulation**.

$$\begin{array}{ccc} G & \xrightarrow{f} & H \\ x & \xrightarrow{\quad} & y \\ \downarrow e & & \downarrow f(e) \\ x' & \dashrightarrow & f(x') \end{array}$$

Yoneda embedding for graphs

Yoneda embedding $\mathbf{y}: \Gamma \hookrightarrow \mathbf{Gph}$:

$$\mathbf{y}_{[0]} = \boxed{\bullet} \qquad \mathbf{y}_{[1]} = \boxed{\bullet \longrightarrow \bullet}$$

$$\mathbf{y}_s: [0] \rightarrow [1] = \left(\boxed{\bullet} \hookrightarrow \boxed{\bullet \longrightarrow \bullet} \right)$$

$$\mathbf{y}_t: [0] \rightarrow [1] = \left(\boxed{\bullet} \hookrightarrow \boxed{\bullet \longrightarrow \bullet} \right)$$

Notation

Yoneda embedding often kept implicit!

Functional bisimulation by lifting

Definition (Functional bisimulation)

f functional bisimulation iff $\forall v, e, \exists k$:

$$\begin{array}{ccc}
 [0] & \xrightarrow{v} & X \\
 s \downarrow & \nearrow k & \downarrow f \\
 [1] & \xrightarrow{e} & Y
 \end{array}$$

i.e.

$$\begin{array}{ccc}
 v & \xrightarrow{f} & f(v) \\
 k \downarrow & & \downarrow e \\
 k \cdot t & \xrightarrow{f} & e \cdot t
 \end{array}$$

- v picks a vertex in X .
- e picks an edge in Y .
- Commutation says $s(e) = f(v)$.
- Existence of k :
 - antecedent of e by f ,
 - whose source is v .

Interlude: lifting

Definition

- In any category, $s \sqsupseteq f$ iff $\forall v, e, \exists k$:

$$\begin{array}{ccc}
 A & \xrightarrow{v} & X \\
 s \downarrow & \nearrow k & \downarrow f \\
 B & \xrightarrow{e} & Y.
 \end{array}$$

- Similarly:

$$S^{\sqsupseteq} = \{f \mid \forall s \in S, s \sqsupseteq f\} \quad \sqsupseteq F = \{s \mid \forall f \in F, s \sqsupseteq f\}.$$

Proposition (obvious)

$$f \text{ functional bisimulation} \Leftrightarrow s \sqsupseteq f \Leftrightarrow f \in \{s\}^{\sqsupseteq}.$$

A transition category with basic labels

- Let A be the considered set of labels.
- Presheaves over Ω_A :

$$\dots \quad \begin{array}{c} [a] \\ \left. \begin{array}{c} \uparrow \\ s^a \end{array} \right\} \left. \begin{array}{c} \uparrow \\ t^a \end{array} \right\} \\ [0] \end{array} \quad \dots \quad (a \in A)$$

- Any $X \in \widehat{\Omega}_A$ has
 - a set of vertices $X[0]$,
 - a set of a -transitions $X[a]$ for all $a \in A$, each with its source and target.

A transition category with basic labels

Definition (Functional bisimulation)

$$\begin{array}{ccc}
 [0] & \xrightarrow{v} & X \\
 s^a \downarrow & \nearrow k & \downarrow f \\
 [a] & \xrightarrow{e} & Y
 \end{array}
 \quad \text{i.e.} \quad
 \begin{array}{ccc}
 v & \xrightarrow{f} & f(v) \\
 k:a \downarrow & & \downarrow e:a \\
 k \cdot t^a & \xrightarrow{f} & e \cdot t^a
 \end{array}$$

Equivalently, $f \in \{s^a \mid a \in A\}^\square$.

- Transition types in **Gph**: just [1].
- Here: all $[a]$'s.

Transition categories

Definition

Category with distinguished cospans

$$P \xrightarrow{s} L \xleftarrow{t} Q$$

+ finite completeness, cocompleteness, well-poweredness, images, and tininess of all $P \in \mathbf{P}$.

Let \mathbf{T}_s denote the set of all such $s: P \rightarrow L$.

Definition (Functional bisimulation)

$$\begin{array}{ccc}
 P & \xrightarrow{v} & X \\
 s \downarrow & \dashrightarrow k & \downarrow f \\
 L & \xrightarrow{e} & Y
 \end{array}$$

i.e.

$$f \in \mathbf{T}_s^\square.$$

Interlude: quick introduction to monads

On **Set** for concreteness.

Definition

A **monad** is an endofunctor $\mathcal{T} : \mathbf{Set} \rightarrow \mathbf{Set}$ with natural transformations

$$X \xrightarrow{\eta_X} \mathcal{T}(X) \qquad \mathcal{T}(\mathcal{T}(X)) \xrightarrow{\mu_X} \mathcal{T}(X)$$

satisfying axioms.

Notation

$$\begin{array}{l} X \xrightarrow{\eta_X} \mathcal{T}(X) \\ x \mapsto (x). \end{array}$$

Intuition: $\mathcal{T}(X) =$ terms with free variables in X .

Interlude: quick introduction to monads

Example

CCS syntax:

$$\mathcal{T}_{\text{CCS}}(X) \ni P, Q ::= (x) \mid (P|Q) \mid a.P \mid \bar{a}.P \mid \dots \quad (x \in X).$$

Interlude: monads

Let $\langle n \rangle = \{1, \dots, n\}$.

Intuition

- Morphism $e: \langle n \rangle \rightarrow \mathcal{T}(X)$ = n -tuple of terms with free variables in X .
- $e_i = e(i) \in \mathcal{T}(X)$.
- On morphisms, $\mathcal{T}(f): \mathcal{T}(X) \rightarrow \mathcal{T}(Y)$ = renaming of free variables.

Kleisli composition \approx substitution

Definition (Kleisli composition)

Given $f: X \rightarrow \mathcal{T}(Y)$ and $g: Y \rightarrow \mathcal{T}(Z)$:

$$X \xrightarrow{f} \mathcal{T}(Y) \xrightarrow{\mathcal{T}(g)} \mathcal{T}(\mathcal{T}(Z)) \xrightarrow{\mu_Z} \mathcal{T}(Z).$$

- $\mathcal{T}(\mathcal{T}(Z))$ terms whose free variables are terms.
- Intuition for μ : remove outer $\langle \! \langle - \! \rangle \! \rangle$'s.

Example

$$b. (\langle \! \langle a.(x) \mid (y) \mid (z) \rangle \! \rangle \mid \langle \! \langle \bar{a}.(t) \rangle \! \rangle) \quad \xrightarrow{\mu} \quad b. (a.(x) \mid (y) \mid (z) \mid \bar{a}.(t))$$

SOS specifications as monads

Idea (Staton): view SOS rules as endofunctors.

Concrete idea, on $\widehat{\Omega}_A$

SOS specification $S \rightsquigarrow$ monad \mathcal{T}_S :

- $\mathcal{T}_S(X)[0]$: terms with constants in $X[0]$,
- $\mathcal{T}_S(X)[a]$: derivations with transition axioms in all $X[b]$'s,
- multiplication $\mathcal{T}_S^2(X)[a] \rightarrow \mathcal{T}_S(X)[a]$: plugging derivations.

Example: CCS

- Take

$$A := 1 + \mathcal{N} + \mathcal{N} = \{\tau\} \uplus \{a \mid a \in \mathcal{N}\} \uplus \{\bar{a} \mid a \in \mathcal{N}\}$$

for some set of names \mathcal{N} .

- Let $\alpha ::= \tau \mid a \mid \bar{a}$.
- $X \in \widehat{\Omega}_A$ any A -labelled transition system.
- Think of:
 - $X[0]$ as a set of **term variables**.
 - $X[\alpha]$ as a set of (typed) **transition variables**.

Example: CCS

- $\mathcal{T}_{\text{CCS}}(X)[0]$: CCS terms with constants in $X[0]$.

$$P, Q ::= (x) \mid (P|Q) \mid a.P \mid \bar{a}.P \mid \dots \quad (x \in X[0])$$

- $\mathcal{T}_{\text{CCS}}(X)[\alpha]$: α -transitions with constants in all $X[\beta]$'s.

$$\frac{x \xrightarrow{e: \alpha} y \text{ in } X}{(e): (x) \xrightarrow{\alpha} (y)}$$

$$\frac{}{\text{in}_P^a: a.P \xrightarrow{a} P}$$

$$\frac{L: P \xrightarrow{\alpha} P'}{L|Q: (P|Q) \xrightarrow{\alpha} (P'|Q)}$$

$$\frac{L: P \xrightarrow{\bar{a}} P' \quad R: Q \xrightarrow{a} Q'}{(L \triangleright R): (P|Q) \xrightarrow{\tau} (P'|Q')} \quad \dots$$

Deeper into CCS

Next few slides:

- concrete examples of transitions,
- operations upon them, e.g., substitution,

with categorical interpretation.

CCS: transition proofs as Kleisli morphisms

Consider the labelled transition system $X := [\bar{a}] + [a]$:

$$\boxed{x \xrightarrow{e:\bar{a}} x' \qquad y \xrightarrow{f:a} y' .}$$

Then the proof (omitting $(-)$'s)

$$\frac{\frac{}{e: x \xrightarrow{\bar{a}} x'} \quad \frac{}{f: y \xrightarrow{a} y'}}{(e \triangleright f): (x|y) \xrightarrow{\tau} (x'|y')}$$

is in $\mathcal{T}_{CCS}([\bar{a}] + [a])[\tau]$ hence yields a morphism $[\tau] \rightarrow \mathcal{T}([\bar{a}] + [a])$.

Remark

Linear use of variables.

CCS: transition proofs as Kleisli morphisms

Other example:

$$\frac{\frac{}{e: x \xrightarrow{\bar{a}} x'}}{\frac{}{(e|y): (x|y) \xrightarrow{\bar{a}} (x'|y)}}}{(e|y|y): (x|y|y) \xrightarrow{\bar{a}} (x'|y|y)}$$

yields a morphism $[\bar{a}] \rightarrow \mathcal{T}([\bar{a}] + [a])$.

Remark

Non-linear use of variables.

CCS: substitution

Plugging the proof below left in e on the right

$$\frac{}{out_z^a: \bar{a}.z \xrightarrow{\bar{a}} z} \quad \frac{\frac{}{e: x \xrightarrow{\bar{a}} x'} \quad \frac{}{f: y \xrightarrow{a} y'}}{}{(e \triangleright f): (x|y) \xrightarrow{\tau} (x'|y')}$$

where $z \in X[0]$, yields

$$\frac{\frac{}{out_z^a: \bar{a}.z \xrightarrow{\bar{a}} z} \quad \frac{}{f: y \xrightarrow{a} y'}}{}{(out_z^a \triangleright f): (\bar{a}.z|y) \xrightarrow{\tau} (z|y')}$$

CCS: substitution, categorically?

The proofs

$$\frac{}{\text{out}_z^a: \bar{a}.z \xrightarrow{\bar{a}} z} \qquad \frac{\frac{}{e: x \xrightarrow{\bar{a}} x'} \quad \frac{}{f: y \xrightarrow{a} y'}}{(e \triangleright f): (x|y) \xrightarrow{\tau} (x'|y')}$$

are morphisms

$$[\tau] \xrightarrow{e \triangleright f} \mathcal{T}_{\text{CCS}}([\bar{a}] + [a]) \qquad [\bar{a}] \xrightarrow{\text{out}_z^a} \mathcal{T}_{\text{CCS}}[0].$$

How to model substitution?

Kleisli composition.

CCS: substitution, categorically?

The substitution from before

$$\frac{}{\text{out}_z^a: \bar{a}.z \xrightarrow{\bar{a}} z} \qquad \frac{\frac{}{e: x \xrightarrow{\bar{a}} x'} \quad \frac{}{f: y \xrightarrow{a} y'}}{}{(e \triangleright f): (x|y) \xrightarrow{\tau} (x'|y')}$$

amounts to

$$\begin{array}{ccc} \mathcal{T}_{\text{CCS}}([\bar{a}] + [a]) & \xrightarrow{\mathcal{T}_{\text{CCS}}([\text{“out}_z^a\text{”}, \eta_{[a]}])} & \mathcal{T}_{\text{CCS}}(\mathcal{T}_{\text{CCS}}([0] + [a])) \\ \uparrow e \triangleright f & & \downarrow \mu \\ [\tau] & & \mathcal{T}_{\text{CCS}}([0] + [a]) \end{array}$$

Proof substitution = Kleisli composition.

Bonus: models

Bonus

Models for a SOS specification = **Algebras** for the monad.

Definition

A **\mathcal{T} -algebra** is a map of the form $\mathcal{T}(X) \rightarrow X$ satisfying axioms.

Intuition: interpretation of the syntactic operations and SOS rules.

Summary

Basic set up

- Transition category \mathcal{C} (\approx transition systems and simulations)
- Monad $\mathcal{T} : \mathcal{C} \rightarrow \mathcal{C}$ (\approx SOS specification = set of SOS rules)
- Morphisms in Kleisli category of \mathcal{T} : transition proofs.
- Kleisli composition: proof substitution.
- \mathcal{T} -algebras: models.

Congruence of bisimilarity

Will follow from:

Theorem

Up to suitable hypotheses, if $a: \mathcal{T}(X) \rightarrow X$ is a \mathcal{T} -algebra and $f: R \rightarrow X$ is a functional bisimulation, then so is

$$\mathcal{T}(R) \xrightarrow{\mathcal{T}(f)} \mathcal{T}(X) \xrightarrow{a} X.$$

Intuition

- If $R[0] = \{(x, y) \in X[0] \times X[0] \mid \dots\}$,
- then $\mathcal{T}(R)[0] =$ terms with free variables in R , i.e.,

$$\{C[(x_1, y_1), \dots, (x_n, y_n)] \mid \forall i, (x_i, y_i) \in R[0]\}.$$

- $\sim \mathcal{T}(R)$ is the context closure of R .

Hypothesis 1: compositionality

Generally a vague concept (thanks for asking!).

Definition

An algebra $a: \mathcal{T}(X) \rightarrow X$ is **compositional** iff it is a functional bisimulation.

$$\begin{array}{ccc}
 P & \xrightarrow{v} & \mathcal{T}(X) \\
 s \downarrow & \nearrow k & \downarrow a \\
 L & \xrightarrow{e} & X
 \end{array}$$

Morally: any transition $C[x_1, \dots, x_n] \xrightarrow{\alpha} x'$ decomposes as

$$\frac{\dots \quad x_i \xrightarrow{\alpha_i} y_i \quad \dots}{C[x_1, \dots, x_n] \xrightarrow{\alpha} E[y_1, \dots, y_n]} .$$

Congruence of bisimilarity

Will follow from:

Theorem

If X is a *compositional* \mathcal{T} -algebra and $f: R \rightarrow X$ is a functional bisimulation, then so is

$$\mathcal{T}(R) \xrightarrow{\mathcal{T}(f)} \mathcal{T}(X) \xrightarrow{a} X,$$

up to further hypotheses.

It now suffices to prove that $\mathcal{T}(f)$ is a functional bisimulation.

Standard proof method (simplified)

- f is just first projection.
- Consider any $C[(x_1, y_1), \dots, (x_n, y_n)] \in \mathcal{T}(R)$.
- Given transition from $C[(x_1, y_1), \dots, (x_n, y_n)]$ decomposes as in

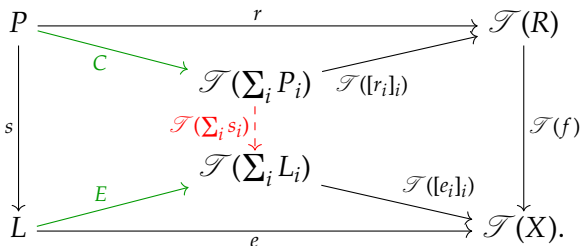
$$\begin{array}{ccc}
 C[(x_1, y_1), \dots, (x_n, y_n)] & \xrightarrow{\mathcal{T}(f)} & C[x_1, \dots, x_n] \\
 E[(e_1, f_1), \dots, (e_n, f_n)] : L \downarrow & & \downarrow E[e_1, \dots, e_n] : L \\
 D[(x'_1, y'_1), \dots, (x'_n, y'_n)] & \xrightarrow{\mathcal{T}(f)} & D[x'_1, \dots, x'_n].
 \end{array}$$

- R is a bisimulation, so find (f_1, \dots, f_n) as shown.
- That's the intuition. In practice:
 - transition contexts E are not first-class citizens,
 - \rightsquigarrow induction on C .

In the abstract framework

$$\begin{array}{ccc} P & \xrightarrow{r} & \mathcal{T}(R) \\ \downarrow s & & \downarrow \mathcal{T}(f) \\ \tilde{L} & \xrightarrow{e} & \mathcal{T}(X). \end{array}$$

In the abstract framework



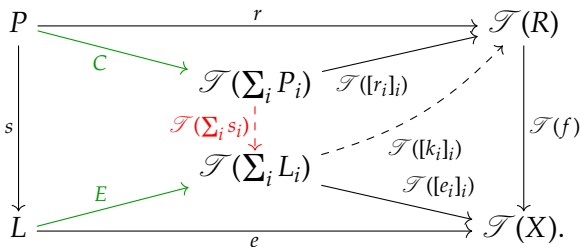
Familiarity!

Intuition: generic = linear context

Any $U \rightarrow \mathcal{T}(X)$ factors as $U \xrightarrow{\xi} \mathcal{T}(Y) \xrightarrow{\mathcal{T}(f)} \mathcal{T}(X)$ with ξ **generic**:

$$\begin{array}{ccc}
 U & \xrightarrow{x} & \mathcal{T}(A) \\
 \xi \downarrow & \nearrow \mathcal{T}(l) & \downarrow \mathcal{T}(k) \\
 \mathcal{T}(Y) & \xrightarrow{\mathcal{T}(h)} & \mathcal{T}(B)
 \end{array}
 \quad (\text{meaning } k \circ l = h)$$

In the abstract framework



\mathbf{T}_S -familiarity

$$\begin{array}{ccc}
 P & \xrightarrow{s} & L \\
 \xi \downarrow & & \downarrow \zeta \\
 \mathcal{T}(Y) & \xrightarrow{\mathcal{T}(f)} & \mathcal{T}(Z)
 \end{array}$$

If ξ and ζ are generic, then $f \in \square(\mathbf{T}_S^\square)$.

Example of \mathbf{T}_s -familiarity: \mathcal{T}_{CCS}

Why would \mathcal{T}_{CCS} be \mathbf{T}_s -familiar?

Example

$$\begin{array}{ccc}
 [0] & \xrightarrow{s} & [\tau] \\
 (\square_1 | \square_2) \downarrow & & \downarrow (\square_1 \triangleright \square_2) \\
 \mathcal{T}_{CCS}([0] + [0]) & \xrightarrow{\mathcal{T}_{CCS}(s^{\bar{a}} + s^a)} & \mathcal{T}_{CCS}([\bar{a}] + [a])
 \end{array}$$

\mathbf{T}_s -familiarity here: $s^{\bar{a}}, s^a \in \mathbf{T}_s$ so $s^{\bar{a}} + s^a \in \square(\mathbf{T}_s^\square)$.

Progression

Standard definition of bisimulation up to context

R progresses to $\mathcal{E}(R)$, where

$$\mathcal{E}(R) := \{(C[P_1, \dots, P_n], C[Q_1, \dots, Q_n]) \mid P_i R Q_i\}.$$

$$\begin{array}{ccc}
 x & R & y \\
 \downarrow & & \vdots \\
 x' & \mathcal{E}(R) & \exists y'
 \end{array}$$

Progression

Standard definition of bisimulation up to context

R progresses to $\mathcal{C}(R)$, where

$$\mathcal{C}(R) := \{(C[P_1, \dots, P_n], C[Q_1, \dots, Q_n]) \mid P_i R Q_i\}.$$

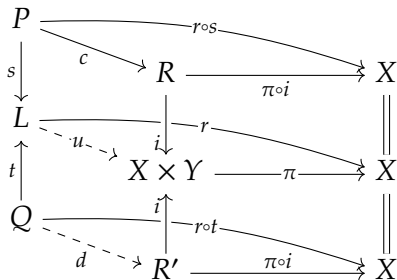
$$\begin{array}{ccc} x & R & y \\ \downarrow & & \vdots \\ x' & R' & \exists y' \end{array}$$

Generalises to R progresses to R' .

Progression in the abstract framework

Definition

- Relations $R, R' \hookrightarrow X \times Y$ in transition category.
- $R \rightsquigarrow R'$ iff



and symmetrically for Y .

Example: bisimulation up to context

$$R \rightsquigarrow \mathcal{T}(R).$$

But wait...

Question

Does $R \rightsquigarrow R$ iff R is a bisimulation?

- Not quite, but artefact of formalism.
- Reason: in $R \rightsquigarrow R$, $R \hookrightarrow X \times Y$ may have **no** transition.
- Good news, we can add them:

Proposition

Under mild hypotheses, factors as

$$R \rightarrow \bar{R} \rightarrow X \times Y$$

with \bar{R} a bisimulation.

Soundness of bisimulation up to context

Theorem

Under hypotheses, $R \rightsquigarrow \mathcal{T}(R)$ entails $\mathcal{T}(R) \rightsquigarrow \mathcal{T}(R)$.

Corollary

Any bisimulation up to context embeds into some bisimulation.

Example with binding: π -calculus syntax

- Need to refine the base category.
- Let's start with the part about syntax:

$$\dots \quad [a] \quad \dots \quad (a \in A)$$

$$\begin{array}{c} \uparrow \quad \uparrow \\ s^a \quad t^a \\ [0], \end{array}$$

i.e., the terminal category **1**.

- $\hat{1} = \mathbf{Set}$: CCS syntax is a monad over sets

$$\mathcal{T}_{CCS}(X) = \{\text{terms with free variables in } X\}.$$

- Known solution (Fiore?): index over finite sets of names.

$$\mathcal{T}_{\pi}(X)(\gamma) = \{\text{terms with free variables in } X \text{ and free names in } \gamma\}.$$

Example with binding: π -calculus syntax

Base category for π -calculus syntax

Morally: opposite of $\mathcal{P}_f(\mathcal{N})$.

- Objects: all $\gamma \subseteq_f \mathcal{N}$.
- Morphisms $\gamma \rightarrow \gamma'$: bijections $\gamma' \rightarrow \gamma$ (think contravariance).

Monad for π -calculus syntax:

$$\mathcal{T}_\pi(X)(\gamma) = \{\gamma \vdash_X P\}$$

where $X \in \overline{\mathcal{P}_f(\mathcal{N})}$.

$$\frac{x \in X(\gamma) \quad f \in \mathbf{Set}(\gamma, \gamma')}{\gamma' \vdash_X (|x|)(f)}$$

$$\frac{\gamma, b \vdash_X P \quad a \in \gamma}{\gamma \vdash_X a(b).P}$$

$$\frac{\gamma \vdash_X P \quad \gamma \vdash_X Q}{\gamma \vdash_X P|Q}$$

$$\frac{}{\gamma \vdash_X 0}$$

$$\frac{\gamma, a \vdash_X P}{\gamma \vdash_X va.P}$$

$$\frac{\gamma \vdash_X P \quad a, b \in \gamma}{\gamma \vdash_X \bar{a}\langle b \rangle.P}$$

Example with binding: π -calculus syntax

Meaning of

$$\frac{x \in X(\gamma) \quad f \in \mathbf{Set}(\gamma, \gamma')}{\gamma' \vdash_X (|x|)(f)} :$$

renaming

- isn't required from all presheaves,
- in particular not from bisimulation relations,
- but **is** required from \mathcal{T}_π -algebras.

In other words: it is a syntactic **operation**.

Example with binding: π -calculus transitions

- Formally add objects for transition types:
 - τ_γ : silent transition between processes with names in γ ,
 - $\bar{a}\langle b \rangle_\gamma$: output b on a , with $a, b \in \gamma$,
 - $\bar{a}(vc)_\gamma$: output **new** c on a , with $a \in \gamma$ but $c \notin \gamma$,
 - ...
- and source and target morphisms

$$\gamma \xrightarrow{s} \tau_\gamma \xleftarrow{t} \gamma \qquad \gamma \xrightarrow{s} \bar{a}\langle b \rangle_\gamma \xleftarrow{t} \gamma \qquad \gamma \xrightarrow{s} a(b)_\gamma \xleftarrow{t} \gamma$$

$$\gamma \xrightarrow{s} \bar{a}(vc)_\gamma \xleftarrow{t} \gamma, c \qquad \gamma \xrightarrow{s} a(vc)_\gamma \xleftarrow{t} \gamma, c$$

- plus compatible morphisms for bijective renaming (next slide).

Example with binding: a few rules

$$\frac{e \in X(\alpha) \quad \gamma \xrightarrow{s} \alpha \xleftarrow{t} (\gamma, \delta) \quad h: \gamma \xrightarrow{\cong} \gamma' \quad k: \delta \xrightarrow{\cong} \delta' \quad \gamma' \cap \delta' = \emptyset}{\langle e \rangle(h, k) : \gamma' \vdash_X \langle e \cdot s \rangle(h) \xrightarrow{(h, k) \cdot \alpha} \gamma', \delta' \vdash_X \langle e \cdot t \rangle(h + k)}$$

Example: renaming a bound name, $k: \{c\} \xrightarrow{\cong} \{d\}$

$$\begin{array}{ccccc} \gamma & \xrightarrow{s} & \bar{a}(vc) & \xleftarrow{t} & \gamma, c \\ h=id_\gamma \uparrow & & \uparrow (id_\gamma, k) & & \uparrow id_\gamma + k \\ \gamma' & \xrightarrow{s} & (id_\gamma, k) \cdot \bar{a}(vc) = \bar{a}(vd) & \xleftarrow{t} & \gamma', d. \end{array}$$

Example with binding: a few rules

$$\frac{\gamma, b \vdash_X P \quad a, c \in \gamma}{in_{b.P}^{a,c} : \gamma \vdash_X a(b).P \xrightarrow{a(c)_\gamma} \gamma \vdash_X [b \mapsto c] \cdot P}$$

- Renaming defined inductively.
- $[b \mapsto c]$ means $\gamma, b \xrightarrow{[id,c]} \gamma$.
- Base case:

$$g \cdot \llbracket x \rrbracket (f) = \llbracket x \rrbracket (g \circ f).$$

Example with binding: a few rules

$$\frac{R : \gamma \vdash_X P \xrightarrow{\bar{a}\langle b \rangle_\gamma} \gamma \vdash_X P' \quad S : \gamma \vdash_X Q \xrightarrow{a(b)_\gamma} \gamma \vdash_X Q'}{R \triangleright S : \gamma \vdash_X (P|Q) \xrightarrow{\tau_\gamma} \gamma \vdash_X (P'|Q')}$$

Familiarity

Proposition

\mathcal{T}_π is a \mathbf{T}_S -familial monad.

Example

$$\begin{array}{ccccc}
 \gamma & \xrightarrow{s} & a(c) & \xleftarrow{t} & \gamma \\
 a(b).(\Box)(id) \downarrow & & \downarrow in_{b.(\Box)(id)}^{a,c} & & \downarrow (\Box)[b \mapsto c] \\
 \mathcal{T}_\pi(\gamma, b) & \xrightarrow{\mathcal{T}_\pi(id)} & \mathcal{T}_\pi(\gamma, b) & \xleftarrow{\mathcal{T}_\pi(id)} & \mathcal{T}_\pi(\gamma, b)
 \end{array}$$

with $b \notin \gamma$.

Familyality

Proposition

\mathcal{T}_π is a \mathbf{T}_s -familial monad.

Example

$$\begin{array}{ccccc}
 \gamma & \xrightarrow{s} & \tau_\gamma & \xleftarrow{t} & \gamma \\
 \downarrow (\square_1)(id) | (\square_2)(id) & & \downarrow (\square_1)(id, id) \triangleright (\square_2)(id, id) & & \downarrow (\square_1)(id) | (\square_2)(id) \\
 \mathcal{T}_\pi(\gamma + \gamma) & \xrightarrow{\mathcal{T}_\pi(s+s)} & \mathcal{T}_\pi(\bar{a}\langle b \rangle + a(b)) & \xleftarrow{\mathcal{T}_\pi(t+t)} & \mathcal{T}_\pi(\gamma + \gamma)
 \end{array}$$

Failure of congruence

- But bisimilarity is not a congruence in π : what fails?
- Congruence theorem holds under the

Crucial hypothesis

The considered algebra $\mathcal{T}(X) \rightarrow X$ is **compositional**, i.e., is a functional bisimulation.

- For π , the considered algebra is

$$\mu_0: \mathcal{T}_\pi(\mathcal{T}_\pi(0)) \rightarrow \mathcal{T}_\pi(0),$$

which is not a functional bisimulation.

Failure of congruence

Adapting a well-known counterexample

- Let $p = (\bar{a}|b)$ (for $a \neq b$) and $f : \{a, b\} \rightarrow \{a\}$.
- Unmatched transition:

$$\begin{array}{ccc}
 (p)[b \mapsto a] & \xrightarrow{\mu_0} & \bar{a}|a \\
 & & \downarrow \tau_{\{a\}} \\
 & & 0|0.
 \end{array}$$

Summary

Main example	General case
cat. of transition systems functional bisimulation	transition category \mathbf{T}_S^\square
SOS specification model partial transition proof	monad algebra Kleisli morphism

- Hypotheses \implies
 - congruence of bisimilarity,
 - soundness of bisimulation up to context.
- Example with binding: π .

Perspectives

- Existing formats \rightsquigarrow instances?
- More general format along the lines of free monads.

Questions

- “Free” familial monads?
 - Why would a free μ be a functional bisimulation?
-
- Other up-to techniques.
 - Related questions, e.g., weak bisimulation, process equations, environmental bisimulation, Howe.
 - Broader scope: analytic monads, to accomodate structural congruence.
 - Go quantitative?

Progression by lifting in cospans

